

**Current Status of the Claims**

This listing of claims will replace all prior versions, and listings, of claims in the application:

**Listing of Claims:**

1. (currently amended)      A method for determining the direction of movement of ~~a motor,~~  
~~especially~~ an electric motor of a transmission actuating mechanism for the select and/or shift  
operation, in which at least one signal of the motor is detected, wherein the direction of  
movement of the motor is validated on the basis of current flow direction by at least one detected  
signal, and wherein in a motor that is de-energized and stationary, the starting current is  
compared to the directional signal of a sensor.
2. (canceled)
3. (previously presented)      The method as described in Claim ~~[[2]]~~ 1, wherein, if the detected  
directional signal for a determined time interval does not agree with the aforementioned flow  
direction of the electric motor, a fault regarding the direction of movement is recognized.
4. (previously presented)      The method as described in Claim 3, wherein in the presence of a  
fault at least one output stage of the transmission actuating mechanism is switched off.
5. (previously presented)      The method as described in Claim 1, wherein, in a brushless  
electric motor, the direction of movement is determined from the sequence of the frequency level  
for the detection of different frequency signals by multiple sensors.
6. (previously presented)      The method as described in Claim 5, wherein the starting current is  
validated via the frequency signals of the sensors starting from an electric motor that is de-  
energized and stationary.

7. (previously presented) The method as described in Claim 6, wherein a check is made of whether the signal edge received as the next one does not correspond to the predetermined flow direction.

8. (previously presented) The method as described in Claim 7, wherein, when the signal edge does not correspond, a fault with respect to direction of movement is recognized.

9. (previously presented) The method as described in Claim 8, wherein, when a fault is recognized, at least one output stage of the transmission actuating mechanism is switched off.

10. (previously presented) The method as described in Claim ~~[[2]]~~ 1, wherein at least one Hall sensor is used as the sensor.

11. (previously presented) A shift motor of a transmission actuator comprising at least one means for validating the direction of movement of the motor, wherein said means measures a detected signal current flow, wherein said means further comprises at least one Hall sensor.

12. (canceled)